



Special features

- Mechanical design identical to EMS20 type
- Strain gauge measuring system
- Tension / Compression
- Built-in signal conditioner with voltage and current output
- Possibility to use both outputs simultaneously
- Power supply: 5 ... 27 VDC

The EMS21 sensor is used for force measuring in the direction of compression and tension. It has a built-in electronic signal conditioner which provides all standard output ranges, both voltage and current. It is also possible to use both outputs simultaneously. The sensor is particularly suitable for measuring forces on machines.

Overview of models

Model	Output (Vout, Iout)	Power supply (DC)
EMS21 – U(0.5 ... 4.5)	0.5 ... 4.5 V	5 ... 27 V
EMS21 – U(2.5 ± 2)	2.5 ± 2 V	5 ... 27 V
EMS21 – U(2 ... 10)	2 ... 10 V	11.5 ... 27 V
EMS21 – U(6 ± 10)	6 ± 4 V	11.5 ... 27 V
EMS21 – I(4 ... 20)	4 ... 20 mA	22 ... 27 V
EMS21 – I(12 ± 8)	12 ± 8 mA	22 ... 27 V

The version of the output as well as the range of the sensor and the direction of the load must be specified in the order. After the setting in the factory, it is no longer possible to change these parameters.

It is possible to use both voltage and current output simultaneously during operation. However, it is practical used only for the output 2 ... 10 V / 4 ... 20 mA or 6 ± 10 V / 12 ± 8 mA and the supply voltage 24 V. With other voltage outputs and smaller supply voltage, the current output is limited.

The adjustment of the sensor (within the permitted tolerances) is only possible for one output, i. e. j. either for voltage or for current. The output specified in the order is set.

Specifications

Parameter	Value	Unit
Rated capacity (F_n)	0.1, 0.2, 0.5 1, 2, 5, 10, 20, 50	kN
Overload - <i>Safe</i> - <i>Ultimate</i> - <i>Permanent static load (recommended value)</i> - <i>Dynamic load (recommended value)</i>	130 150 75 50	% F_n % F_n % F_n % F_n
Rated output tolerance - <i>Voltage output</i> - <i>Current output</i>	± 80 ± 0.16	mV mA
Output load impedance - <i>Voltage output (min)</i> - <i>Current output (max)</i>	2 500	k Ω Ω
Cut-off frequency of built-in amplifier (-3 dB)	200	Hz
Max error - <i>Non-linearity</i> - <i>Hysteresis</i>	0.25 0.25	% F.S. % F.S.
Temperature range (T) - <i>Nominal</i> - <i>Operating</i>	0 ... + 50 - 10 ... + 50	$^{\circ}\text{C}$ $^{\circ}\text{C}$
Temperature drift - $\Delta V_{out} / \Delta T$ (max) - $\Delta I_{out} / \Delta T$ (max)	± 1.5 ± 3	mV / $^{\circ}\text{C}$ $\mu\text{A} / ^{\circ}\text{C}$
Power supply (V_{cc}) - <i>Range</i> - <i>Current consumption (max)</i>	5 ... 27 40	VDC mA
Power supply drift, $V_{cc} = 5 \dots 24$ V - $\Delta V_{out} / \Delta V_{cc}$ (max) - $\Delta I_{out} / \Delta V_{cc}$ (max)	± 20 ± 40	mV / V $\mu\text{A} / \text{V}$
Cable - <i>type</i> - <i>Length</i> - <i>Outer diameter</i>	LifYDY 7x0.05 2 4.5	 m mm
Protection	IP54	
Body material - <i>0.1; 0.2; 0.5 kN</i> - <i>1, 2, 5, 10, 20, 50 kN</i>	Aluminium Stainless steel	

How to order

Common formula for ordering:

EMS21-U/I(output range) – force range – load direction

- Sensor type with type of output:
 - EMS21-U – voltage output
 - EMS21-I – current output
- Voltage output ranges:
 - 0.5 ... 4.5 V
 - 2.5 ± 2 V (zero shifted to 2.5 V)
 - 2 ... 10 V
 - 6 ± 4 V (zero shifted to 6 V)
- Current output ranges:
 - 4 ... 20 mA
 - 12 ± 8 mA (zero shifted to 12 mA)
- Measured force range (kN):
 - 100N, 200N, 500N, 1 kN, 2 kN, 5 kN, 10 kN, 20 kN, 50 kN
- Load direction:
 - Compression
 - Tension
 - Compression/Tension (both)

Examples:

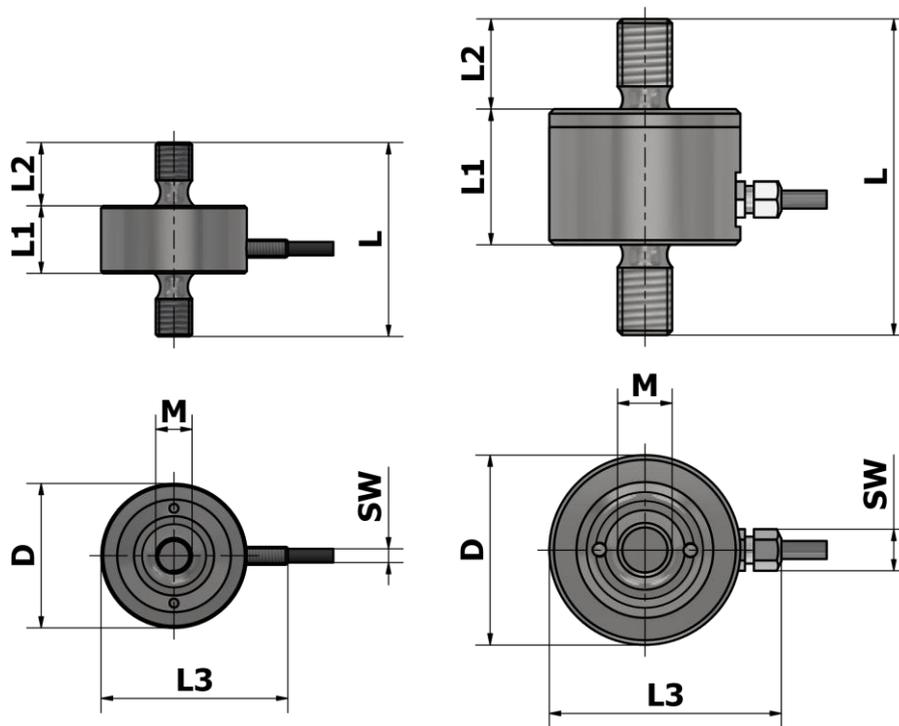
200N sensor with voltage output 2 ... 10V, load direction compression, order:

EMS21-U (2 ... 10V) – 200N – Compression

1kN sensor with current output with shifted zero, load direction Compression and Tension, order:

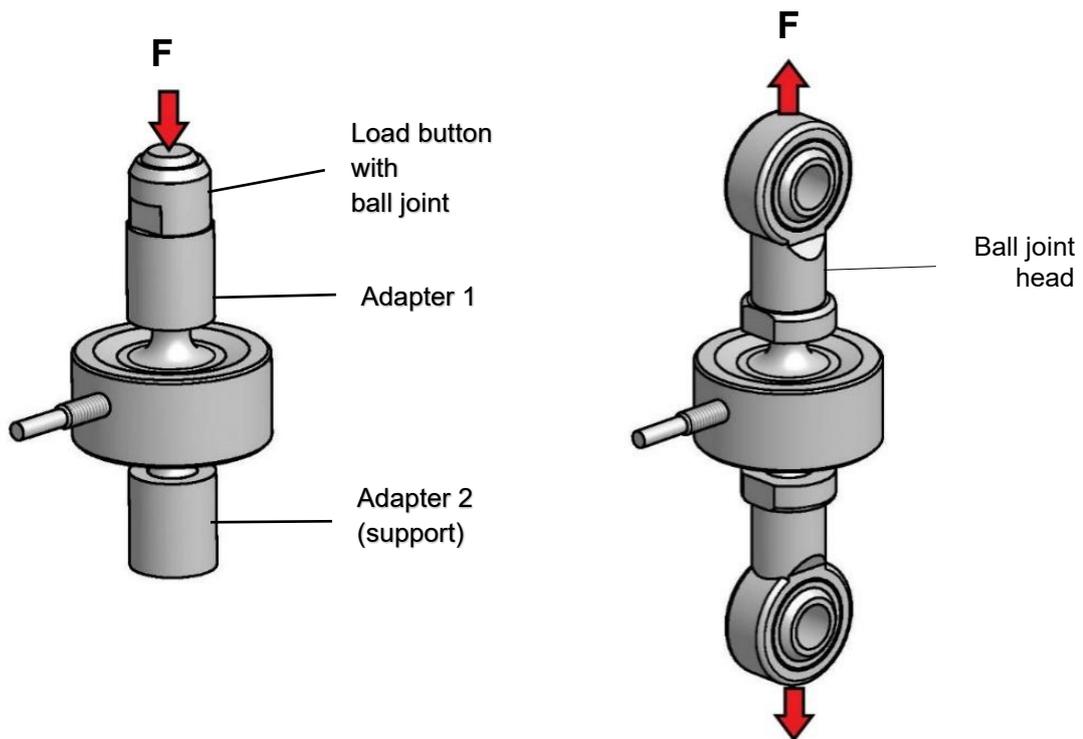
EMS21-I (12 ± 8 mA) – 1kN – Compression/Tension

Outline dimensions



Rated capacity F_n (kN)	D mm	M mm	L mm	L1 mm	L2 mm	L3 mm	SW mm	Mass kg	Deflection, @ F_n (μm)
0.05	18	M4	24	10	7	24	Φ 3	0.04	30
0.1, 0.2, 0.5	28	M6	34	14	10	38	Φ 4	0.05	35
1, 2, 5	32	M8	43	15	14	42	Φ 4	0.1	45
10	38	M10	60	26	17	47	8	0.2	43
20	42	M12	70	30	20	51	8	0.3	56
50	50	M16	86	40	23	59	8	0.6	80

Recommended installation



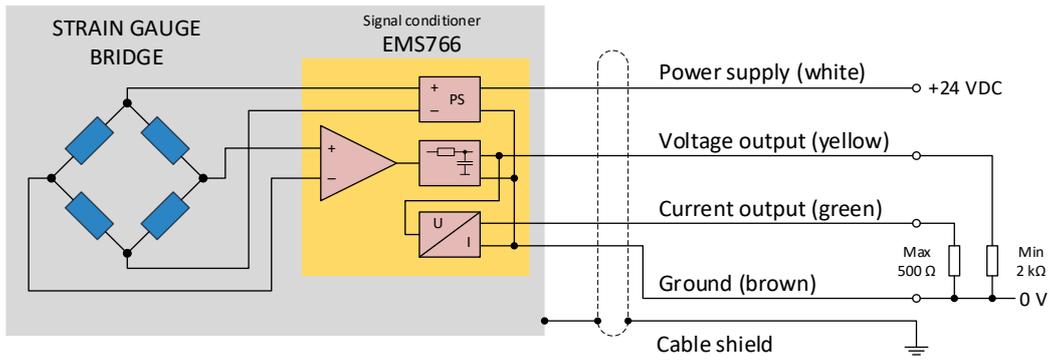
Direction of load COMPRESSION

Direction of load TENSION

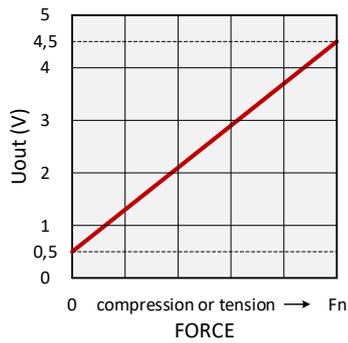
Installation notes:

- The force must only act in the axis of the sensor.
- The sensor must be built in such a way that the force acts only through the threads. Adapter or the ball joint head must not touch the sensor body itself.

Wiring diagram



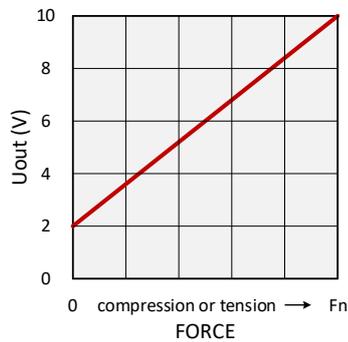
Output characteristics



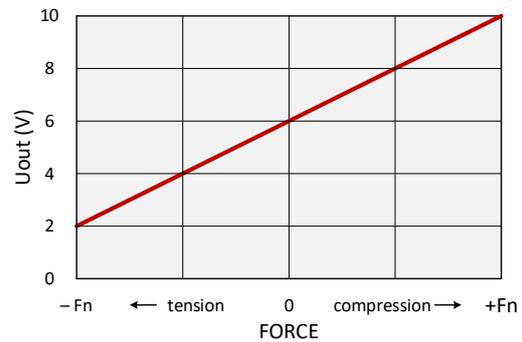
$U(0.5 \dots 4.5 \text{ V})$



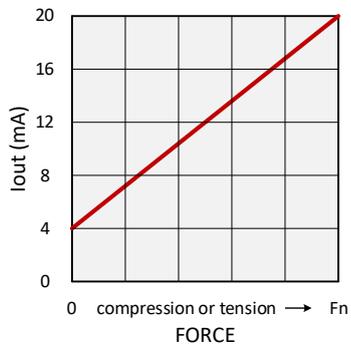
$U(2.5 \pm 2 \text{ V})$
zero shifted to 2.5 V



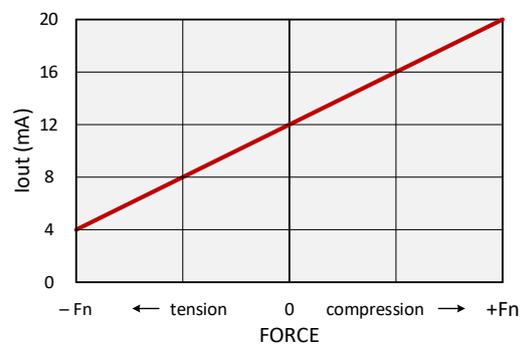
$U(2 \dots 10 \text{ V})$



$U(6 \pm 4 \text{ V})$
zero shifted to 6 V



$I(4 \dots 20 \text{ mA})$



$I(12 \pm 8 \text{ mA})$
zero shifted to 12 mA

Legal information

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